

# **In-Space Autonomous ANTS Production Facility**

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# Systems concepts study results

- Revolutionary Aerospace Systems Concepts
  - GSFC, LaRC, GRC
- Prospecting Asteroids Mission
  - Advanced mission set in the 2020s
  - Identified mission requirements
  - Identified mission functions & capabilities
  - Examined current capabilities & trends
- Back propagated results to current capabilities
  - ART, NBF...



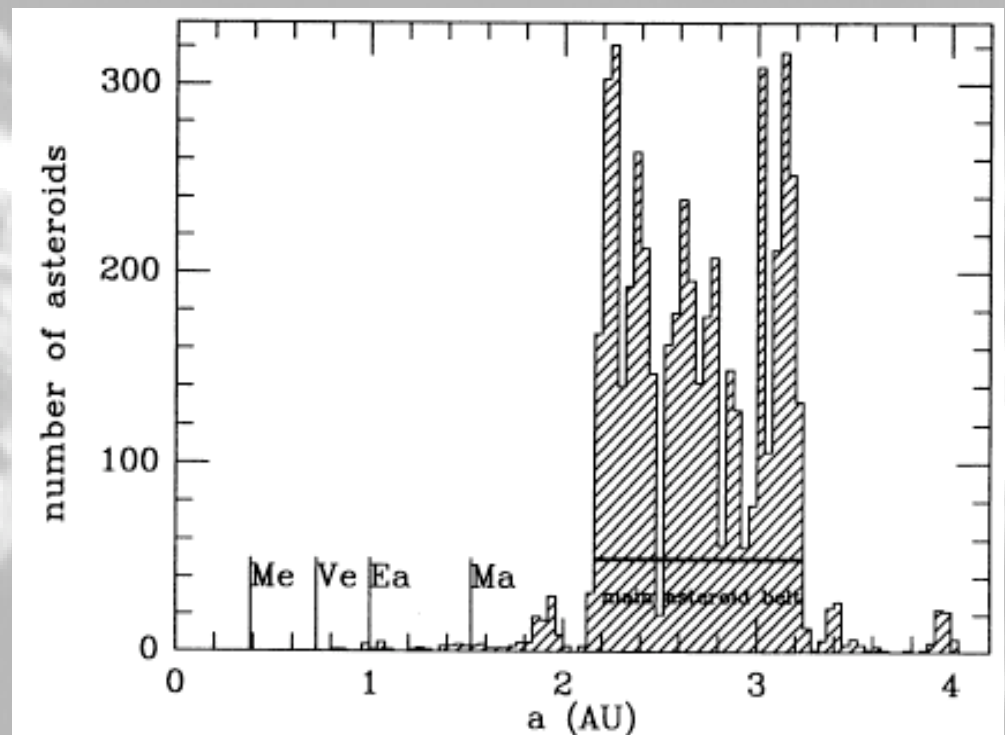
## Main Belt Asteroids

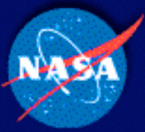
### Main Belt Asteroids Characteristics

- Contains remnant planetesimals from Solar System formation
- $\sim 10^5$ - $10^6$  objects ( $>1$ km diameter)
- Between the orbits of Mars & Jupiter (2.1 AU – 3.3 AU): between inner “rocky” & outer “gaseous” planets
- Surface of largest 1000 observed asteroids is  $\sim 70\%$  the area of Mars.
- The remainder may dwarf the surface area of the Earth.
- Refractory (Fe, Ni, Si) materials dominate inner belt; Volatiles ( $\text{NH}_4$ ,  $\text{CH}_4$ ,  $\text{H}_2\text{O}$ ) abundant in outer belt
- Wide range of processes & history represented
- Both “processed” & “primordial” materials present: Most “primitive” material in Solar System

### Challenging Targets

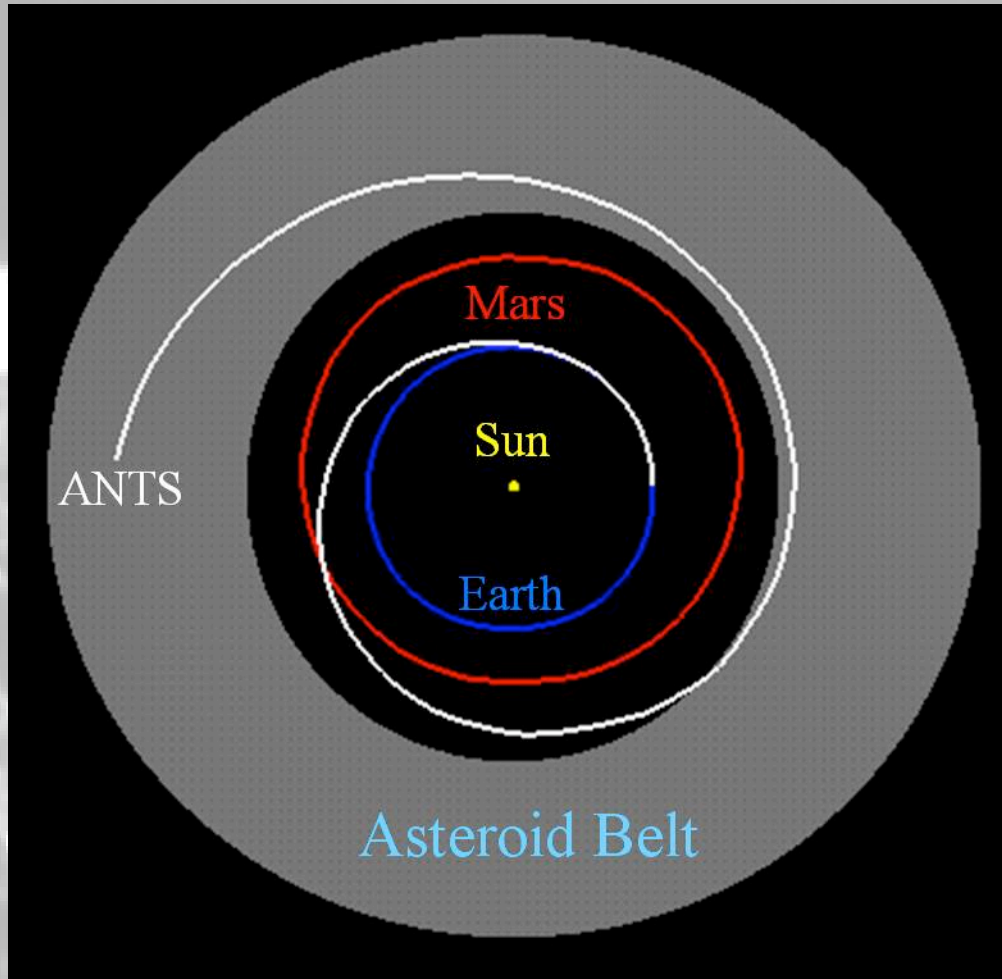
- Thousands of ‘targets of opportunity’
- Far from Earth & the Sun
- Most are small & dark: difficult targets
- Variable shape, gravitational field, and dynamic properties : difficult to “navigate”

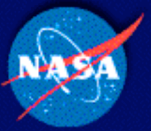




## PAM Navigation: Sailing to the remote targets

### Solar sail trajectory to the Asteroid Belt

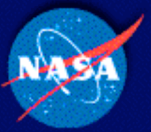




## The ANTS Architecture

- Missions are applications of the Architecture, e.g., RASC studies of the Prospecting Asteroid Mission (PAM) and the Saturn Autonomous Ring Array (SARA)
- Insect hierarchical organization
  - Many types of specialized workers – ‘science craft’
  - Many workers of each type
  - Intelligent swarm interactions
- Fully autonomous – ‘Launch it and forget it’
  - Complex-adaptable-evolvable
  - Integration of body and neural system
- Miniaturization via nanotechnology to pico ( $\leq 1$  Kg) class
- Self-repair capabilities – radically reconfigurable gossamer space frame
- Architectural approach enables technology back propagation
  - Addressable architecture – LCD Screen analogy
  - Near-term manufacturability

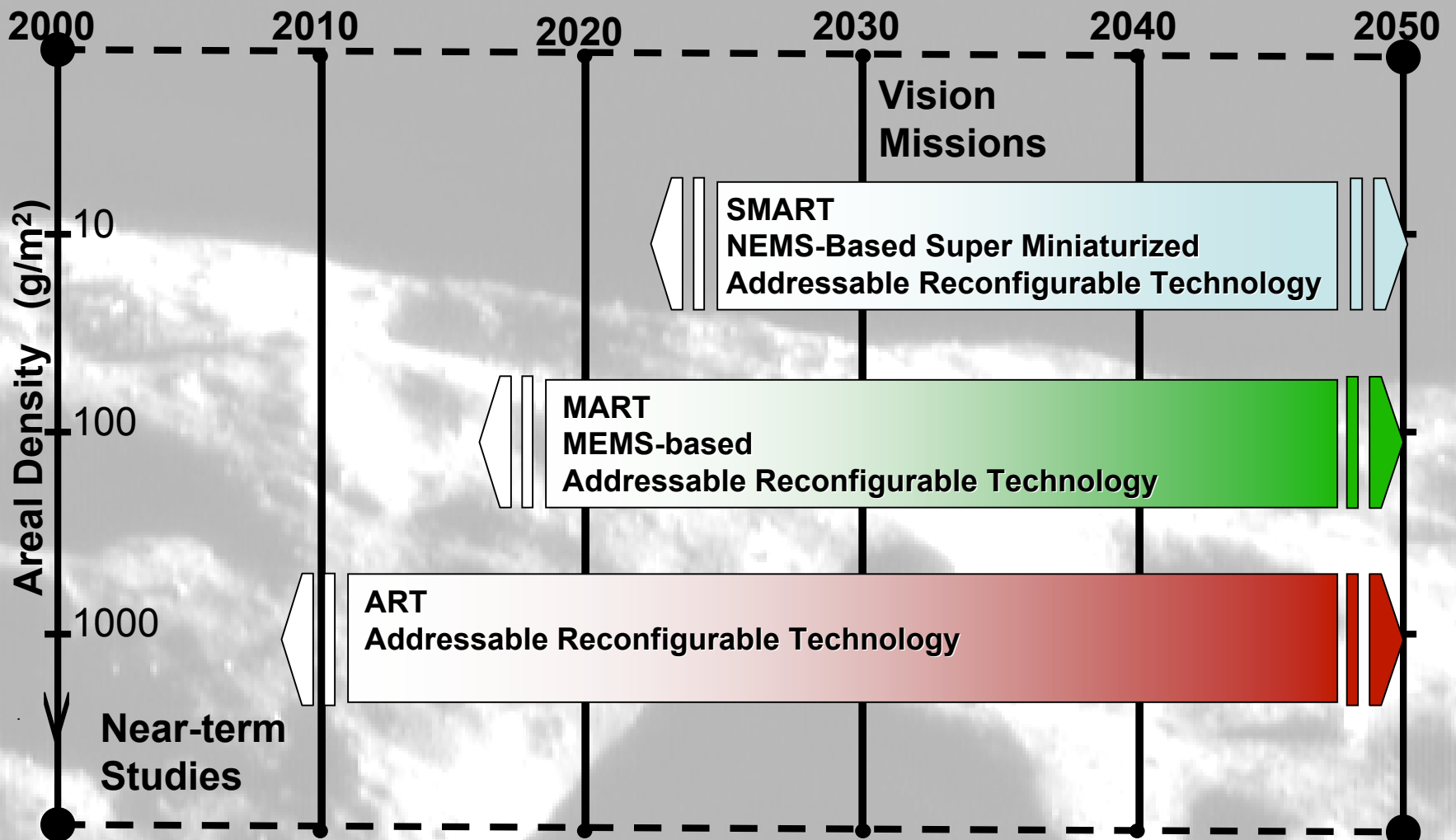




# RASC

REVOLUTIONARY AEROSPACE SYSTEMS CONCEPTS

## ANTS Development Long-Term Enabling Technology Timeline



# ANTS/PAM Needs

- Large numbers of spacecraft
- Low mass, low areal density
- Active shape control
- Standardized, robust parts
- Highly parallel system

# ANTS/PAM

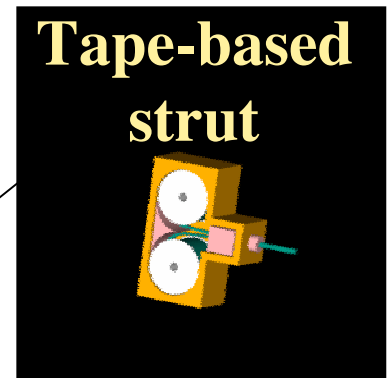
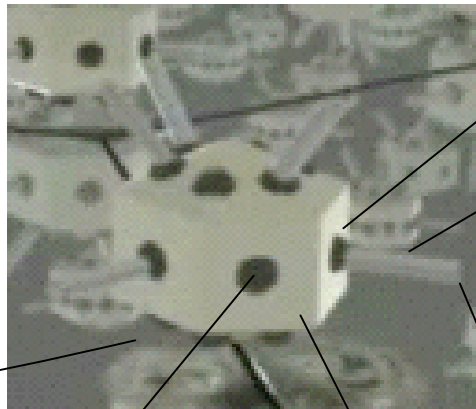
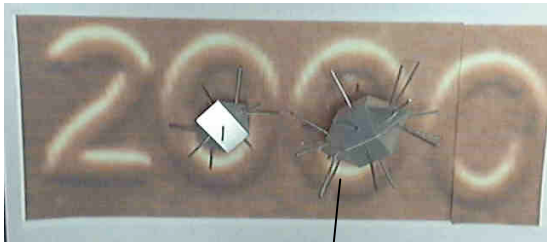
## *Spacecraft Construction*

- Ground based
  - Fabrication, packaging
- Transport to Autonomous Research Facility
- ARF provides infrastructure (e.g. templates)
- Nodes self assemble into Gossamer structures
  - In parallel under local control
- Structures stow themselves
  - Moved around by robotic assembly infrastructure
  - Moved around by helper spacecraft



# Assembly in Space

## *Nodes & Struts*



Extensible/retractable  
strut

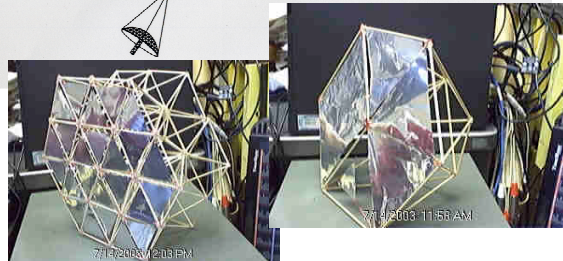
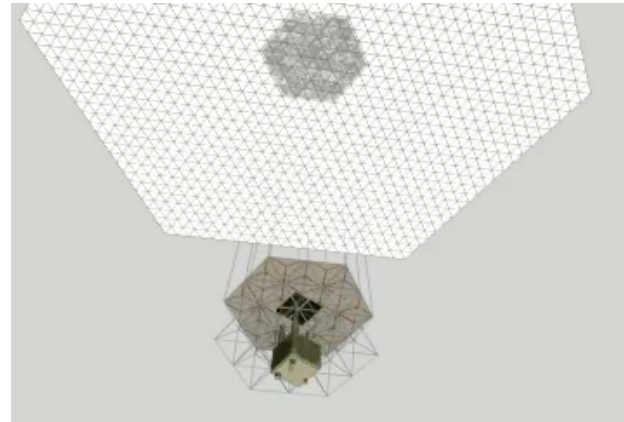
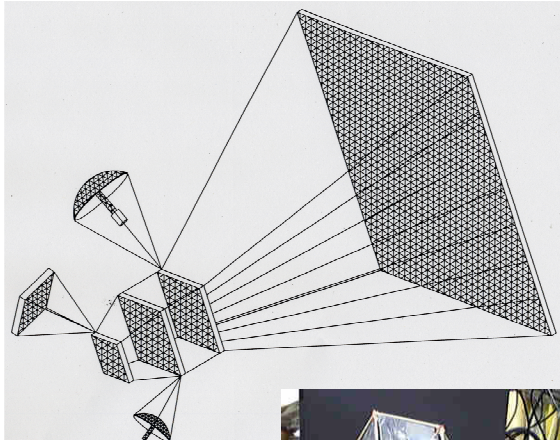
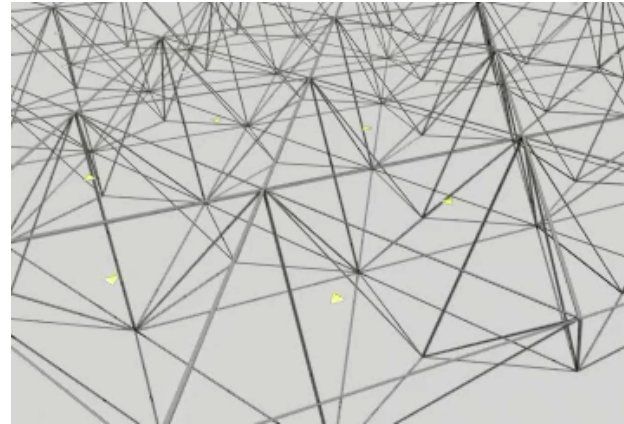
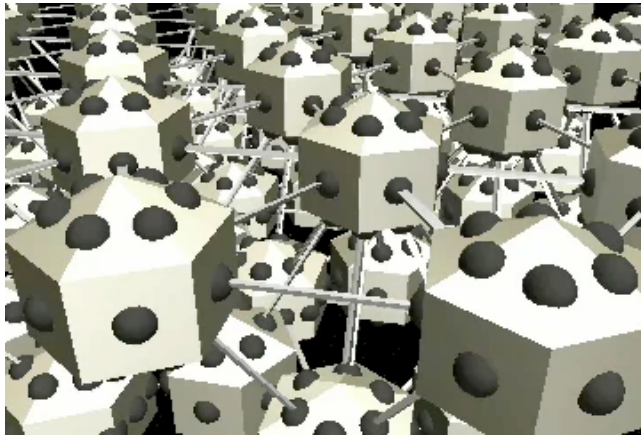
Clamping mechanism on end

Socket for clamp

Node

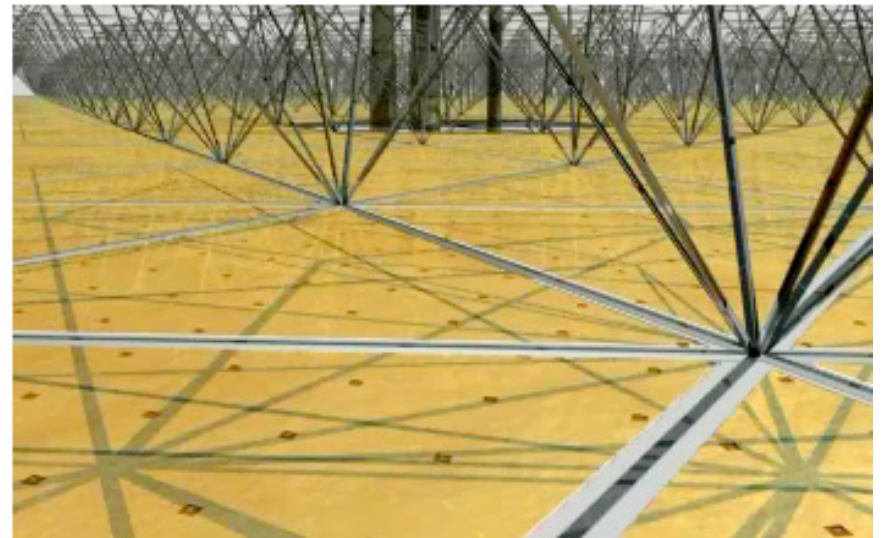
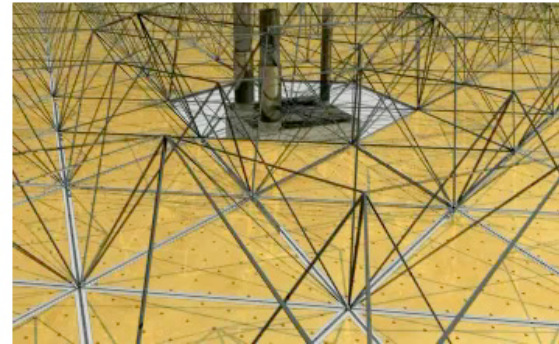
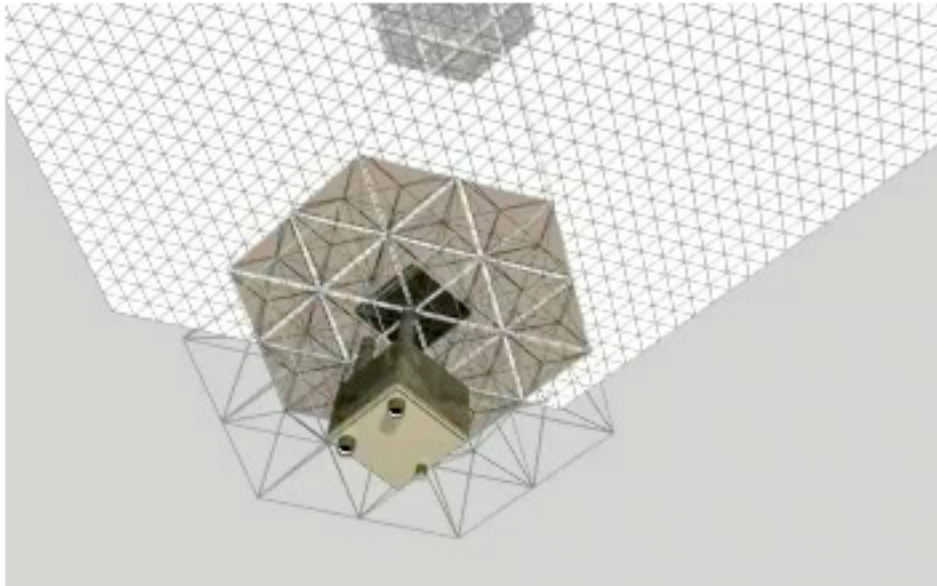
# Assembly in Space

## *Structures*

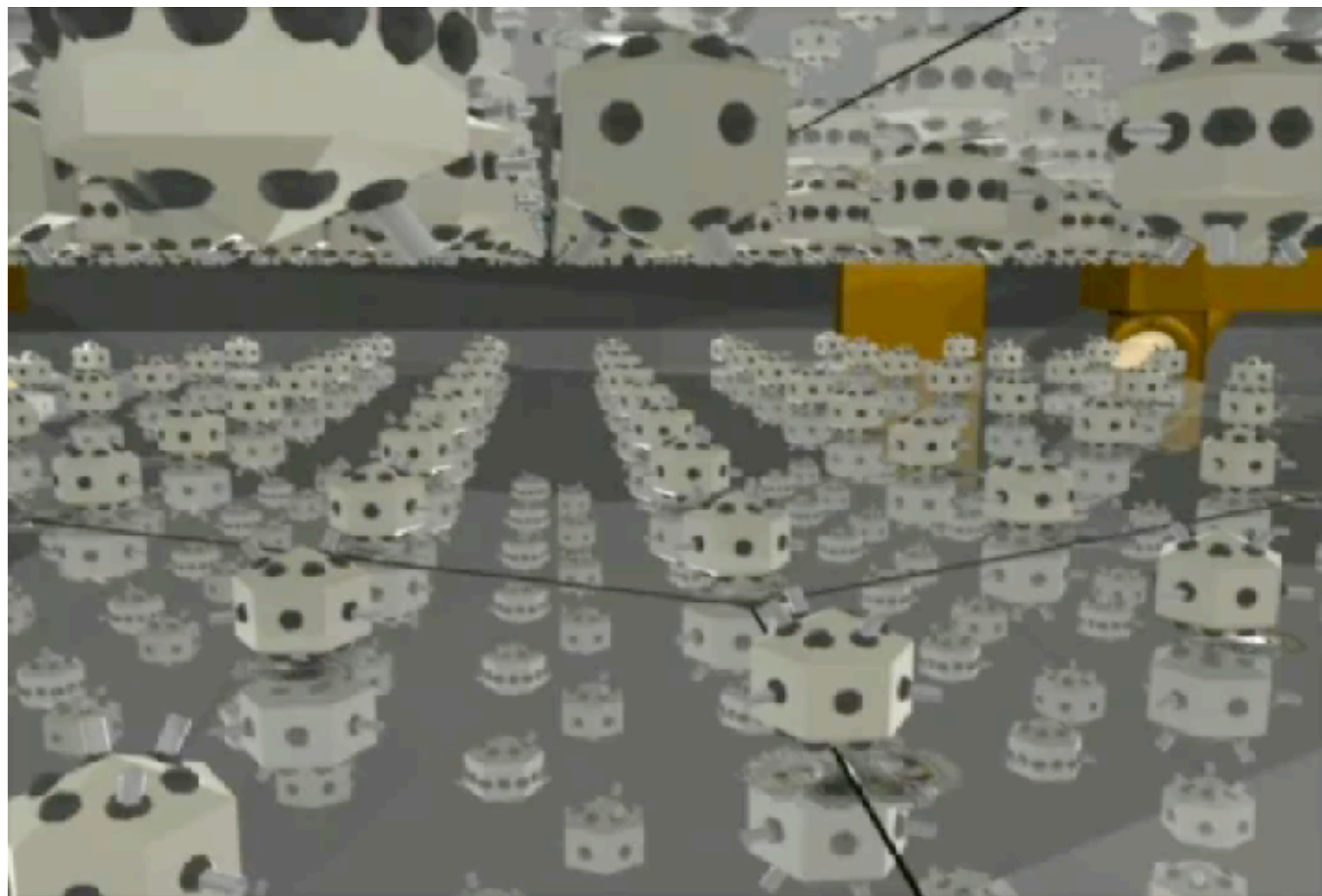


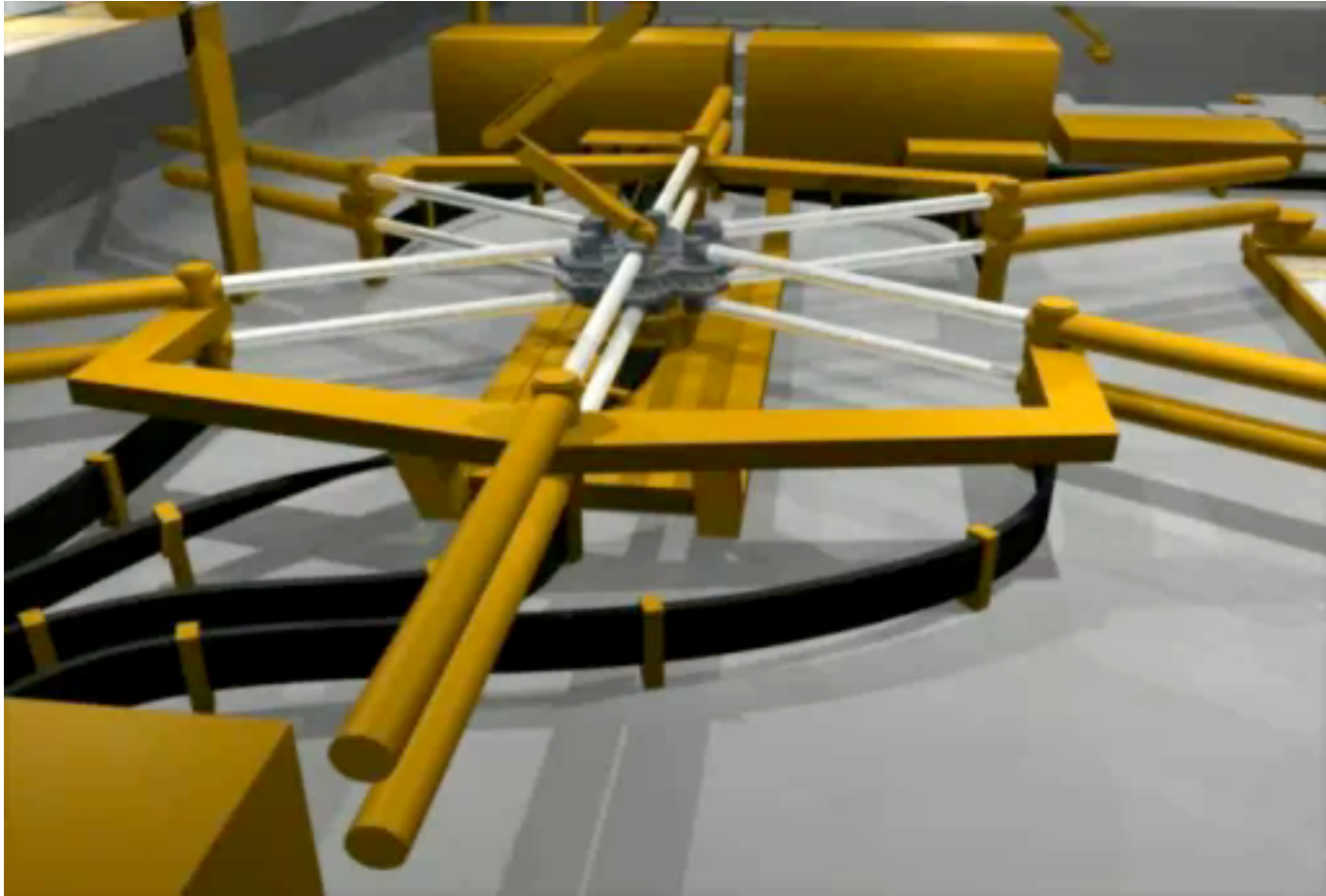
# Assembly in Space

## *The Spacecraft*



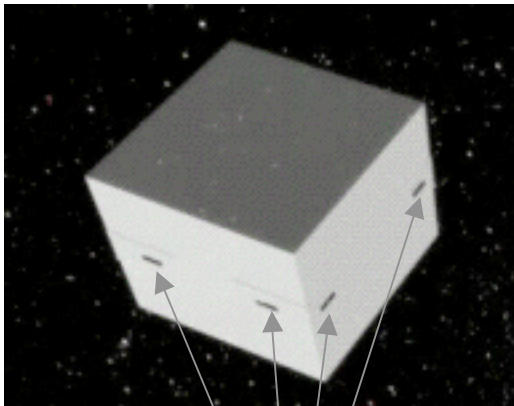




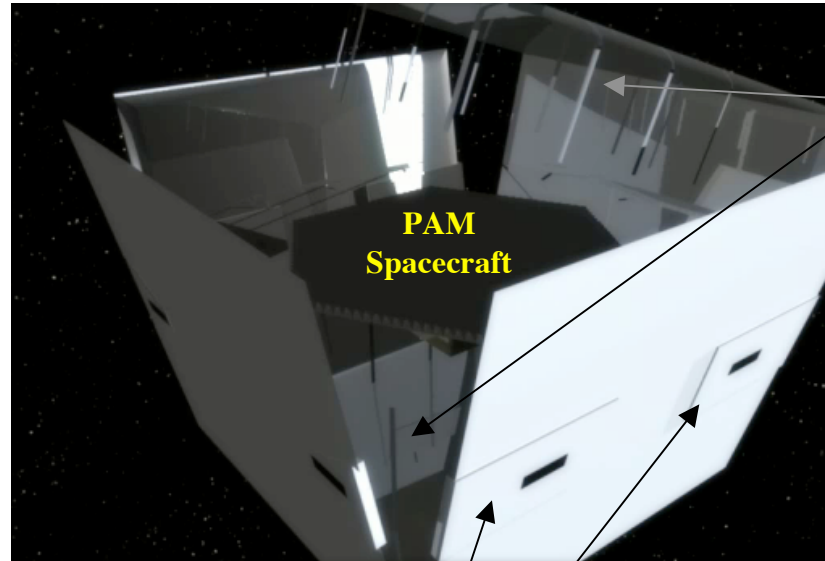


# Assembly in Space

## *Carrier Shell*



Thrusters

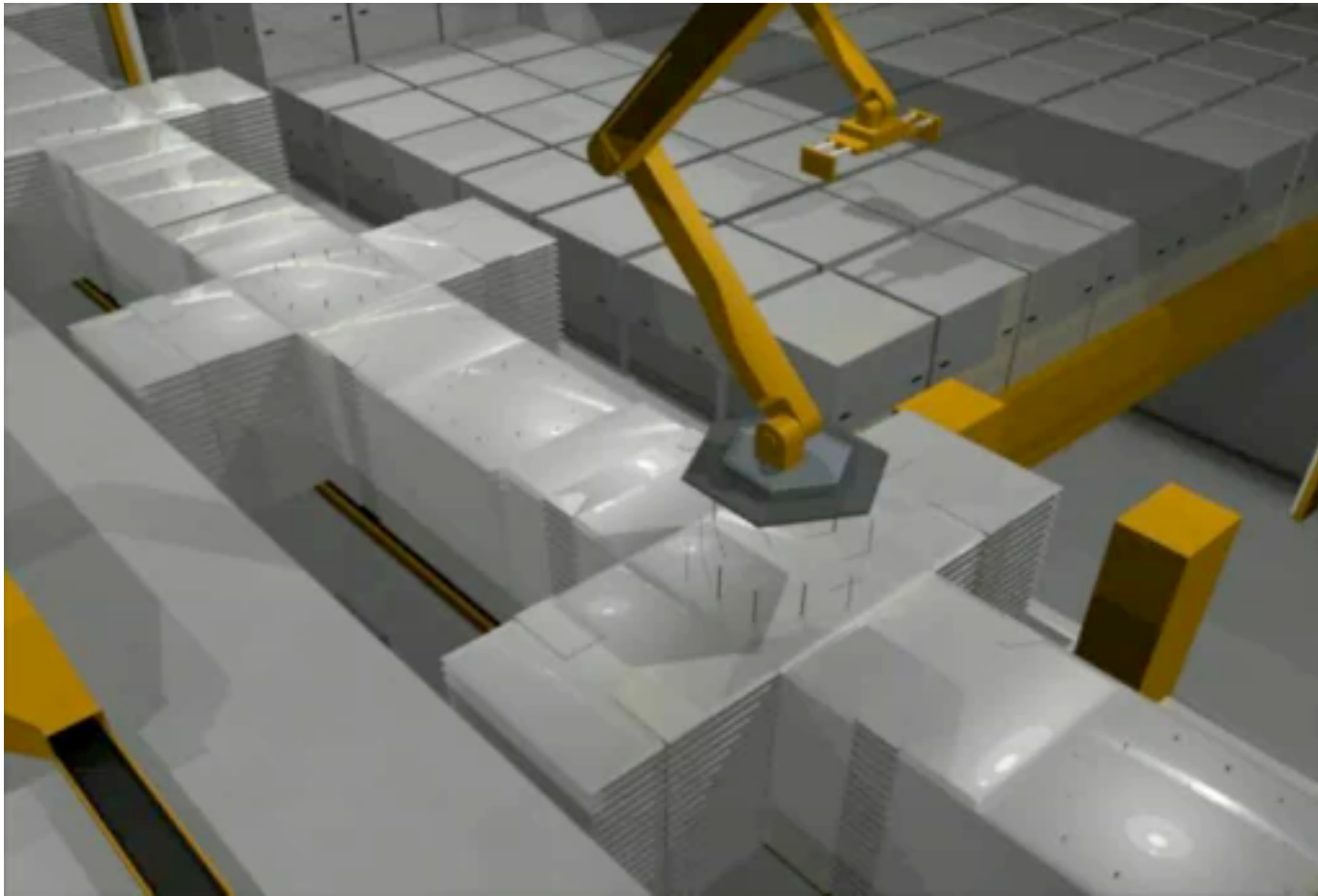


Tethers

Patch Antennas

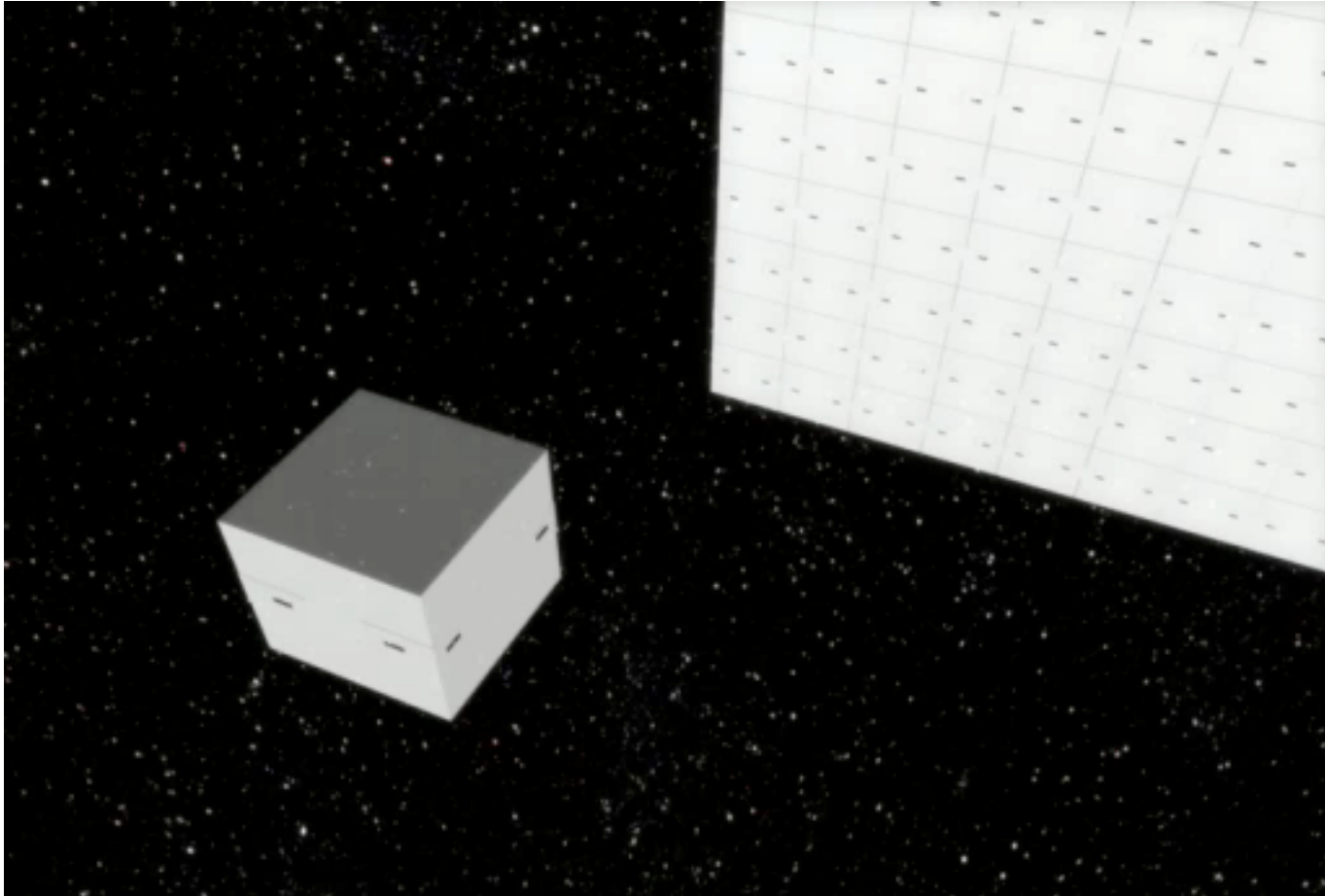
# Assembly in Space

## *Carrier Shell Integration*



# Assembly in Space

## *Deployment from Carrier Shell*





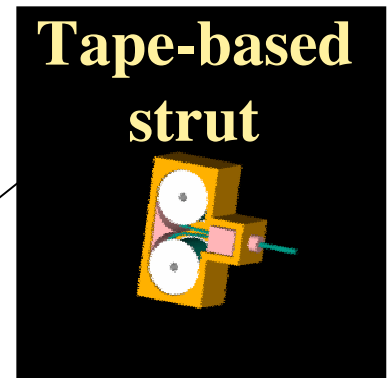
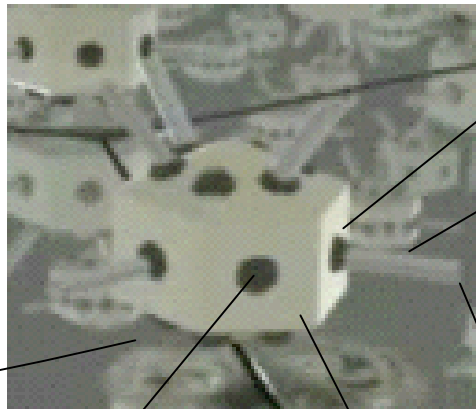
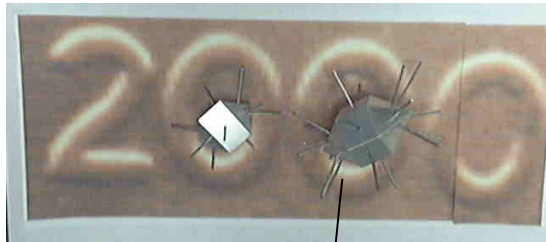
# Conclusion

*ants.gsfc.nasa.gov*

- *In space assembly*
  - *Improves deployment options*
    - *Energetically favorable trajectories (ANTS/PAM)*
    - *Assembly en route or in place*
  - *Separates concerns*
    - *Launch environment hardening*
    - *Spacecraft engineering*
  - *Based on advanced nodal elements*
    - *Can be built within ANTS framework*
    - *Requires some intelligence*
      - *ART, addressable in near-term*
      - *SMART, autonomous in the far-term*
    - *RF signaling*
  - *Creates options for dealing with faults & failures*

# SMART Structures

## *Nodes & Struts*



Extensible/retractable  
strut

Clamping mechanism on end

Socket for clamp

Node